

CS122 Algorithms and Data Structures

MW 11:00 am - 12:15 pm, MSEC 101

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Lecture 15: Graphs (2)

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Depth first search

- n Starting from vertex v
- n Mark v as marked
- n Select u as an unmarked node adjacent to v
- n If no u , quit
- n If u , begin depth first search from u
- n When search from u quits, select another node from v
- n Similar to preorder tree traversal

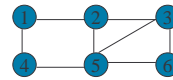
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Breadth first search

- n Starting from node v
- n Identify all nodes adjacent to v
- n Add these to the set
- n Determine set of unvisited nodes which are adjacent to this set
- n Add these to the set
- n Continue until no new nodes are encountered

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An Example



What would the visit orders for DFS(1), DFS(5), BFS(1), BFS(5) look like?

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Unweighted Shortest Path

- n Find the shortest path (measured by number of edges) from a designated vertex S to every vertex
- n Simplified case of weighted shortest path

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Algorithm

- n Starting from node S
- n Distance from S to S is 0, so label as 0
- n Find all nodes which are distance 1 from S
- n Label as distance 1
- n Find all nodes which are distance 2 from S
- n These are 1 step from those labeled 1
- n This is precisely a breadth first search

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Positive Weighted Shortest Path

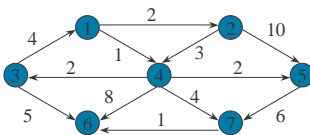
- n Length is sum of the edges costs on the path
- n All edges have **nonnegative cost**
- n Find shortest paths from some start vertex to all vertices
- n similar process to unweighted case
- n **Dijkstra's Algorithm**

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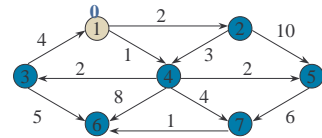
- n Distance at each node v is shortest path distance from s to v using only known vertices as intermediates
- n An example of a **Greedy Algorithm**
- n Solve problem in stages by doing what appears to be the best thing at each stage
- n *Decision* in one stage is not changed later

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start at v_1 , all distances are infinity



mark v_1 is removed from the toBeChecked set, with distance 0



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Ford Algorithm

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FordAlgorithm(G, s)
  for all vertices  $v$  do
     $\text{dist}[v] = \infty$ ;  $p[v] = \text{NULL}$ ;
   $\text{dist}[s] = 0$ ;
  while there is  $(v, u)$  that  $\text{dist}[u] > \text{dist}[v] + \text{weight}(v, u)$  do
     $\text{dist}[u] = \text{dist}[v] + \text{weight}(v, u)$ ;
     $p[u] = v$ ;
  endwhile
    
```

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Spanning tree

- n subgraph of G
- n contains all vertices of G
- n connected graph with no cycles

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Minimum spanning tree

- n spanning tree with minimum cost
- n only exists if G is connected
- n number of edges is $|V|-1$
- n two greedy methods
 - Kruskal's algorithm
 - Prim's algorithm
- n differ in how next edge is selected

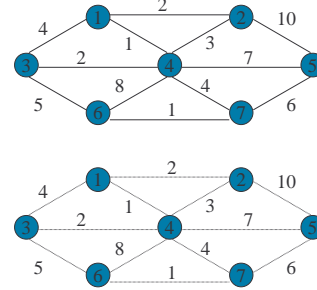
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Kruskal's algorithm

- n select edge with smallest weight as accept the edge if it does not cause a cycle
- n determining if it causes a cycle: essentially the equivalence class (union/find) problem
- n two vertices belong to the same set iff they are connected in the current spanning forest

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Construct MST for this graph using Kruskal's algorithm



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Prim's algorithm

- n grow the tree in successive stages
- n in each stage, one node is picked as the root, we add an edge, and thus a vertex is added to the tree
- n have a set on vertices in the tree and a set that is not in the tree

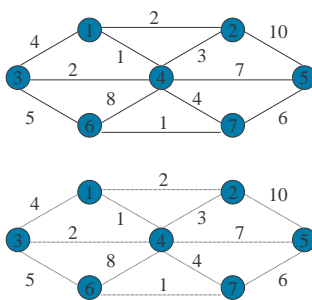
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Prim's algorithm (cont.)

- n at each stage, a new vertex to add to the tree is selected by choosing edge (u, v) such that the cost of (u, v) is the smallest among all edges where u is in the tree and v is not
- n Build spanning tree starting from v_1
- n Result in the same spanning tree as that given by the Kruskal algorithm

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Construct MST from v_1 for this graph using Prim's algorithm



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