

## HW 1 Answers for Selected Problems

1)

$$1.11 \omega = \frac{3000(2\pi)}{60} = 314.16 \frac{\text{rad}}{\text{sec}}. \text{ Period } P = \frac{2\pi}{\omega} = \frac{60}{3000} = \frac{1}{50} \text{ sec.}$$

1.14  $x = 0.005 \sin(6t)$ ,  $\dot{x} = 0.005(6) \cos(6t) = 0.03 \cos(6t)$ . Velocity amplitude is  $0.03 \frac{m}{s}$ .  
 $\ddot{x} = -6(0.03) \sin(6t) = -0.18 \sin(6t)$ . Acceleration amplitude is  $0.18 \frac{m}{s^2}$ . Displacement, velocity and acceleration all have the same frequency.

$$1.15 f = 0.2x$$

$$2) \phi(t) = \frac{2}{3}e^{-3t} + 2t - \frac{2}{3}$$

$$3a) \omega = -\frac{2\tau_f}{J}t + \omega_0$$

$$3d) \theta_{final} = \frac{J\omega_0^2}{4\tau_f}; \text{ Note: you can solve for this analytically or graphically}$$

Supplemental Problem Set 1:

$$1.12 \omega = 5 \frac{\text{rad}}{s}. \text{ Period } P = \frac{2\pi}{\omega} = \frac{2\pi}{5} = 1.257 \text{ s. Frequency } f = \frac{1}{P} = \frac{5}{2\pi} = 0.796 \text{ Hz.}$$

$$1.13 \text{ Speed} = \frac{40(5280)}{3600} = 58.6667 \frac{ft}{s}. \text{ Frequency} = \frac{58.6667}{30} = 1.9556 \text{ times per second.}$$

$$4a) y(t) = \frac{F}{b} \left( 1 - e^{-\frac{b}{m}t} \right)$$

$$4b) y(t) = Ae^{-2t} + \frac{6}{\sqrt{592}} \sin(12t - \tan^{-1}(6)) = \frac{9}{37} \left( e^{-2t} - \cos(12t) + \frac{1}{6} \sin(12t) \right)$$

$$4c) x(t) = \frac{1}{50} e^{-10t} + \frac{1}{5}t - \frac{1}{50}$$

To be worked by 8/26:

$$3.5 (v_0 \sin \theta)t_H, t_H = \frac{-2v_{0y} \pm \sqrt{4v_{0y}^2 + 8gH}}{2g}, v_{0y} = v_0 \cos \theta, v_0 = \sqrt{\frac{2gL}{\tan \theta}}$$

$$3.8 m\ddot{x} = \frac{R_3}{R_2 R_1} M - mg$$

$$3.9 mL^2 \ddot{\phi} - mgL \sin(\phi) = 0$$

3.12

a) the mass  $m_1$  will lift  $m_2$  if  $2m_1 - m_2 \sin(\theta) > 0$

b) the mass  $m_1$  will lift  $m_2$  if  $1 - (\mu_d \cos(\theta) + \sin(\theta)) > 0$

$$3.13 \dot{v} = \frac{f}{m_c + 2m_w + 2\frac{I_w}{r_w^2}} = 4.032 \frac{m}{s^2}$$

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$$3.19 I_e \dot{\omega}_1 = T_1 - \frac{m_2 g R}{N} + \frac{m_3 g R}{N} = T_1 - \frac{g R}{2} (m_3 - m_2)$$

$$3.28 \text{ This problem ignores the wheel inertia. } (2m_r + m_f + m_b) \dot{V} = (2m_r + m_f + m_b) g \sin(10^\circ)$$

$$3.31 (mR^2 + I) \dot{\omega} = R f \cos(\phi)$$

$$3.39 a_{G_x} = \frac{23.544 \mu_s \cos(\theta)}{4.6 - \mu_s} - g \sin(\theta)$$

Supplemental Set 2:

$$3.10 \ddot{x}_B = -\frac{2}{3}g = -6.54 \frac{m}{s^2}; \ddot{x}_A = \frac{1}{3}g = 3.27 \frac{m}{s^2}$$

$$3.11 m_e \dot{v}_A = F_A - \frac{(m_L + m_C)}{2} g \text{ where } m_e = \frac{I_B}{R_B^2} + \frac{I_C}{4R_C^2} + \frac{m_L + m_C}{4}$$

$$3.20 I_e = I_s + I + mR^2$$

$$3.29 \left( m_1 + m_2 + \frac{I}{R^2} \right) \ddot{x} = m_1 g \sin(\beta) - m_2 g \sin(\phi)$$

$$3.34 a_{G_x} = g \sin(\theta) - \mu_d g \cos(\theta)$$